



Application Note: KEEL in Autonomous Vehicles (9/23/2003)

Objective:

The concept of autonomous vehicles has been around for decades. Only recently are we seeing their introduction into the market.

In its broadest definition, an autonomous vehicle is one that operates totally on its own. It could be a plane, a water-based vehicle or any type of land-based vehicle.

A more limited view of an autonomous vehicle would include subsystems within a vehicle that operate without external influences. Using this description, there have been autonomous subassemblies around for years.

An individual component that operates without any other control signals could be considered an autonomous component.

The definition of an autonomous vehicle is open to more debate when one considers that even an autonomous vehicle that operates mostly on its own may still get some direction from external sources. It may get a new job to perform, or it may get new information that causes it to adjust how it operates.

In this application note we will allow almost all definitions of autonomous, in that we will include a stand-alone vehicle that takes no external input as well as vehicles and sub-assemblies that take any amount of external inputs.

The definition of an autonomous vehicle will include any vehicle that makes one or more judgmental decisions on its own using a reasoning approach similar to that of a human.

The human brain has been segmented into left brain and right brain activity. The left brain handles the analytical functions and the right brain handles the subjective functions.

An autonomous vehicle will be expected to handle both left brain and right brain activities. A digital calculator has been used as an example of left brain functionality and a slide rule has been used as an example of right brain functionality. The digital calculator gives an exact answer given a set of inputs. The slide rule gives an approximate answer based on interpreting the inputs.

Judgmental decisions for humans require the interpretation of a number of pieces of information that may interact.



The human mind interprets the importance of each input, each problem domain, and each relationship and balances the system to make a decision or take a relative action.

An autonomous vehicle will be expected to make the same judgmental decisions as a human.

Simple judgmental decisions can be handled with straight line logic: IF, THEN, ELSE, or WHILE, or other test and compare functions.

More complex decisions have required complex formulas to be developed and tested. These take time to develop and additional time to test.

They are brittle and resist modification without starting the development and test phase over and over again.

Other solutions, like the use of neural nets and fuzzy logic, can be used to address some of the judgmental decisions. They resist explanation, however.

Neural nets are systems trained to match certain patterns. When the pattern is not an exact match, there is a potential for making the wrong choice. And because there is no "reasoning" involved, it is difficult to validate.

Fuzzy logic goes through fuzzification and defuzzification processes to determine an answer. This approximation approach using geographic domains is reproducible, but not necessarily explainable with a rule based model.

KEEL technology provides a new model for making judgmental decisions that mimics the human's ability to balance a number of problems that must be addressed simultaneously to make the best overall set of decisions for the system.

KEEL technology allows the autonomous vehicle or subassembly to make judgmental decisions on its own.

Just like humans, KEEL based systems can take direction from external sources that can change how the autonomous vehicle will perform.

Inputs to KEEL based systems from external sources can be given different levels of trust and can be given different levels of authority, just like human systems.

Autonomous vehicles will have to respond to information by making judgmental decisions about how to trust what it sees or hears. Just like human systems have to be aware of possible trickery.



KEEL systems can be constructed to be flexible regarding trust, or they can accumulate trust. Both designs will be appropriate for autonomous vehicles.

KEEL systems can react to risk. Risk assessment can be used to adjust the rule based model operating in the KEEL engine.

This could be recognized internally and it could be tuned externally.

Human systems have self preservation built into them at some level. An autonomous system can have this built in at the factory and left static, or it can be tuned or controlled from external sources.

KEEL based designs for the cognitive sections of autonomous vehicles allow the support of very complex systems. It would be difficult, if not impossible, to create them with straight line code.

The graphical design of KEEL based systems does not require the construction of brittle code. KEEL based systems are created to balance the importance of information and to define interactions between ideas. These systems tend to be organic designs that do not break when new information is added to the system.

Autonomous vehicles have to adapt to changing environmental conditions. They have to react to changing importance of information. Decisions and actions are relative, rather than binary in most cases.

Autonomous vehicles are often faced with limited processor and memory requirements. The small footprint of KEEL engines make them a good choice for the creation of complex cognitive solutions, even in a limited microprocessor.

Autonomous vehicles are often constructed with networks of distributed microprocessors, each responsible for segments of the system.

Cognitive decisions often require that inputs come from all sources. Sometimes inputs come from locations external to the autonomous vehicle.

KEEL technology is architecture neutral, in that information can come from anywhere. Just like a human system, a human can get information from the television, the radio, the internet, etc, as well as from the human's five senses.

KEEL based autonomous vehicles can make judgmental decisions on their own and operate completely without external intervention, or they can accept any types of external direction to be part of a larger system.



In addition to just operational decisions, autonomous vehicles are usually part of a larger system (part of an autonomous army or part of an emergency response team). In addition to performing specific tasks, their objective may be to inform others.

For example, a drone spy plane will be responsible for gathering and delivering intelligence.

Many intelligence-gathering functions require judgmental decisions about what to report and when to report.

KEEL based systems can perform the same judgmental decisions according to a flexible set of rules that adapt to the information at hand.

These decisions will adapt to environmental variables as well as soft variables like threats, risk, and information value.

The KEEL engine can balance the information value against its own value, collateral damage, risks and threats according to a predefined rule set.

The rules could be developed ahead of time without the stress of the moment.

Because KEEL engines are self contained, cognitive engines that operate on a set of rules, autonomous vehicles can be constructed to enable the upgrade of the rules while the system is in operation.

Because an autonomous vehicle will commonly go through different stages of its operation, it may be appropriate to have a state machine switch KEEL engines as it progresses through these different stages.

For example: One set of cognitive processes might be appropriate while an autonomous vehicle is in for maintenance, another while it is on its way to a mission, and another when it is performing intelligence gathering, and another when it is performing a specific task.

A distributed system of multiple KEEL engines may have a state machine associated with each.

Because a single KEEL design can be duplicated in a number of different languages that interpret information in the same way, it is possible to model the cognitive processes of the autonomous vehicle in several environments.

It could be embedded in the autonomous vehicle.

It could be implemented in a simulator.

It could be displayed on the internet.



Because only one design is required for the cognitive processes, this can be a large time savings if this feature is required.

KEEL technology can be deployed in autonomous vehicles to make the same kinds of judgmental decisions and take the same relative actions as a human operator.

KEEL technology has a simple API that makes it specifically valuable as an add-on to an existing system. In this manner it can be a backup to human operation in some cases.

Market:

The market for completely autonomous vehicles is just beginning.

Its growth has been limited by limitations in cognitive technology.

Smart subsystems in the automobile industry are now being planned.

The concept of drive by wire and fly by wire are now being developed.

Increased threats to pilots and passengers are demanding new ways to insure that hijackings do not happen.

Increased traffic on our highways is demanding new approaches to controlling traffic.

The ability of human drivers to manage the increased speed and increased traffic is limited.

The following business drivers support the use of KEEL technology in autonomous vehicles:

Reduced Engineering Design Cost & Time

Reduced Start-up/Commissioning Cost & Time

Optimization of Product Performance/Life to the Task

Increased Machine Performance/Speed - Production Rates

Increased Differentiation of Their Products

Reduced Maintenance Cost & Time

Increase Machine/Process Uptime (OEE)



Reduced Project Risk

Increased Market Coverage

Improved Internal Efficiency - Reduced Fixed Expense

Improved Access to Information

The following buying factors are addressed with KEEL technology in autonomous vehicles:

Ease of Use

Time to Market

Flexibility

Extensibility / Scalability

Desire for Special Features

Performance

Options

Complex Systems

Enterprise Connectivity

Quality

The desire to Learn

Safety

Expectations of the Future

Reduce or Eliminate Other Costs

Considerations:

The schedule for evaluating the data

When complex cognitive systems are being created, the designer needs to consider the time sensitivity of input and output data.

In human systems, humans may try to postpone decisions until all the relevant data is available. When pressed, however, humans can react to demands that drive them to make instant decisions. In a KEEL system, the designer may need to have the system "adapt" to changing demands.



The flexibility of the KEEL system design allows for normal conservative operation and still adapts to emergency situations.

The system designer needs to consider when the data should be evaluated. Options could be to trigger the evaluation on a scheduled basis; it could be polled by a higher level authority; it could operate on a change of state from one of its sensors; or it could be continuously running.

Human interaction with the solution

In cases where KEEL engines participate with humans as part of an overall system, consideration should be given to the human interface characteristics of the system.

KEEL engines can trigger the dialog, or the dialog can be initiated by the human.

KEEL engines can provide continuous analog output which can be translated into human readable form or as stimulation to HMI tools.

KEEL engines can accept input from any source, as long as it is translated to the normalized format required by the KEEL engines.

The system designer will consider how and when the dialog between the human and the KEEL engine will be scheduled.

The ability to create complex cognitive solutions in a timely manner

Using the KEEL toolkit, it is possible to develop complex cognitive solutions in a short timeframe.

Software features are built into the toolset that allow the cognitive design to be structured in a manner that makes it easy to integrate the KEEL engine(s) into a variety of architectural models. In many cases, these tools allow the glue logic to be created once and be able to support changes to the cognitive model.

The KEEL-FBD tool allows the staged development of complex models in a manner that automatically creates the glue logic. This is another feature that supports rapid development of complex systems.

Architecture Independence

KEEL engines are discrete information processing engines.

In many cases they will be part of a larger system.



Just like humans in a factory, in an army, or on a team, there is interaction between individuals and between devices and equipment. Computer protocols and network architectures have been developed in a manner that somewhat duplicates the development of human language.

People developed different languages to satisfy different needs: voice for people to communicate verbally; sign language for those that cannot hear; telephone and video conferencing for distance communication.

Computer based protocols have been developed to satisfy different needs: ASCII for simplicity; XML for structure; asynchronous / synchronous / isochronous for flexibility, speed, and time determinism.

KEEL engines can participate with any of these linkages, as long as the data can be normalized to meet the needs of the KEEL engines.

KEEL engines can sit at any point in any architecture. In this way KEEL engines can be integrated into almost any architecture. The simple API enables this valuable attribute.

The "importance" of information

A key aspect of any KEEL based system is the dynamically changing importance of information.

In simple systems, there may be no changing importance of information. These types of systems might be built with hard coded solutions or discrete logic.

Cognitive solutions, however, usually deal with complex relationships where information is being interpreted in different ways; in different parts of the same problem.

Cognitive problems often deal with both strategic (future) and tactical (now) problems at the same time. Questions about what to do now and not destroy future opportunities are often addressed. This requires a balancing of information to obtain the best outcome.

Diagnostics and prognostics require that a system adapts its operation to performance variables. If you have difficulty breathing, then breathing becomes more important.

Performance of the system

Different applications require different levels of performance for the KEEL engines.



Some real time control applications may require that information is constantly being evaluated and operated upon.

There will be other times when information changes relatively slowly and therefore does not merit constant evaluation.

There are a variety of techniques to balance performance and system complexity when creating KEEL based solutions.

The evolution of the KEEL engine over time

KEEL engines are often developed over time. New pieces of information are added to the design when it is apparent that they contribute to the interpretation of the data provided.

Compsim's KEEL Toolkit provides a number of services to enable enhancements to the engine over time without impacting the glue logic. This saves software development effort.

The KEEL FBD tools allow a complex system to be developed in stages and integrated and tuned as separate components.

The KEEL toolkit incorporates the idea of merge-able objects or decision-making modules.

There are other cases where the model doesn't need to expand, but only needs to be tuned when relationships between information change.

KEEL engines can be created as "classes" in some languages.

The value of "explainable actions"

Many systems can benefit from an engine that creates explainable decisions and actions.

This allows the systems to be audited for their performance in order to tune them over time.

It is possible to have KEEL engines monitor other KEEL engines and potentially provide a feedback mechanism to achieve optimal operation.

There are other cases where there are demands for the creation of explainable actions. This insures that a code of ethics is integrated into the design. Without the ability to decompose every action and every decision, there is the ability to create a system that does not meet the needs of society.



So, KEEL based systems, because they are rule based, can explain why any action was taken or decision was made.

Even though the rules are defined graphically, by inserting a snapshot of the inputs back into the design, the reasoning can be displayed.

Who and how the KEEL actions are monitored

KEEL based systems offer several methods for monitoring their performance.

First, because all KEEL actions are visible and explainable in the development environment, they are available for analysis within the tool environment.

Second, because a KEEL engine is a rule based system, it will always respond the same way to an input. An XML schema exists that defines the format for an XML file produced by the real-world device or software applications. If the device or software application logs the input data in this format, it can be read back into the KEEL Toolkit where the reasoning can be reviewed and explained.

The system designer has the responsibility for determining when and how the data is logged and reviewed.

Certain applications may demand more auditing to insure that performance is satisfactory.

It is also likely that new data will enter the application space. This may trigger reviews of performance.

As in human systems, novice operators or players may require closer review than experienced operators or players. The same is true with a KEEL engine.

Consideration for how the KEEL engine(s) fits in the "chain of command"

In some cases KEEL engines will participate as components of a larger system.

They can perform administrative roles by interpreting information in a consistent manner and responding with consistent command decisions.

They can perform subservient roles by accepting direction from above and adapting the commands to modify their actions.



They can sit in the middle of a chain, by accepting commands from above and reviewing status from below. They can modify their own strategy according to the rules provided to them and the information they observe on their own.

They can make requests to humans and devices above them in the chain-of-command, and can deliver commands to humans and devices below. They can collaborate with their peers according to the rules that dictate responsibility.

Should it be appropriate, the KEEL engines can develop their own levels of trust in collaborative environments. The system designer will determine the communication protocols and the flexibility of the system.

Normalizing the data

KEEL engines operate on normalized data (0 to 100) values that can be either integer or floating point, as defined by the KEEL project.

While this suggests a linear range of normalized input data, the inputs can drive a curve which allows the data to be interpreted in almost any way.

In this manner a single normalized input value can be interpreted according to any number of independent curve relationships.

Much of the development work in architecting a KEEL solution is spent defining the relationships between information. Because this is all done graphically, there is no need to write "code" to see the results of the analysis.

The level of "trust" attached to input information

Many judgmental decisions are made by including a level of trust that the information is correct. When the level of trust is diminished, then the information may be given a lower level of importance in the overall solution.

KEEL engines can include the level of "trust" as an input to the system. How this is interpreted is the responsibility of the system designer.

The concept of risk associated with the decisions and actions associated with the system

Many cognitive decisions need to incorporate risk into the decision-making model.

Risk can be included as an input to a KEEL engine.

How risk participates in the decision-making model, is the responsibility of the system designer.



The responsibility for the overall system remains with the solution architect

The system architect is responsible for the overall architecture of the system.

This will include segmentation of the system, determining when and how the KEEL engines will be scheduled.

The cognitive model for interpreting the input data and causing decisions and actions to be promoted is also the responsibility of the system designer.

How time and space relationships might contribute to the solution

Time and space often impact the importance of information when making cognitive decisions. KEEL supports these concepts with its "clipper" features.

This allows decisions and actions to be tuned for different times and locations.

In cases where an optimal solution is being targeted, such as the time to send a message or the time to shoot at a moving target, then tools to support these kinds of decisions are required. They are built into the KEEL toolkit and available to the system designer.

System architecture

The system architecture is the definition of the relationships between all system components.

The cognitive segment is usually just part of the system. The system architecture defines the layout for performance, flexibility, extensibility, cost, resources, etc.

The system architecture is often the result of a balancing act: balancing time to market, resources, performance, and cost. The system architecture is driven with an objective where the features are defined. The objective is addressed by identifying potential solutions: collections of components and methods of tying them together.

KEEL technology can be integrated into the architecture from the beginning, or it can be an "add-on". Because individual KEEL engines are architecture neutral, they can be integrated into an overall architecture at different times; even after a program is completed.

The potential for autonomous operation



Because KEEL engines can interpret information in a human-like manner, and direct relative actions to be taken based on that interpretation, KEEL based systems have the potential to operate without human intervention.

Alternatively, KEEL based systems can operate as either backups to human operators, giving advice or recommendations, or they can provide the primary decision-making engines that are backed up by humans.

The outputs from the system

The outputs from a KEEL engine are normalized values between 0 and 100. This information may have to be transformed into other forms for use by the external controls or monitoring equipment.

KEEL could generate control signals.

KEEL engines interpret information and provide outputs that represent a balancing of the inputs. These values can be used to generate complex commands in the form of control signals to other equipment.

KEEL could generate information for other KEEL engines.

A common practice is to segment a system into multiple KEEL engines. It is likely that one KEEL engine will provide data to the input(s) of other KEEL engines.

The KEEL FBD tool assists in connecting KEEL engines into a single solution.

KEEL engines could also be distributed across a network or in multiple tasks where messaging or data sharing could provide the mechanism for one KEEL engine to feed others.

KEEL could provide inputs to other systems (non-KEEL).

The outputs from a KEEL engine could be supplied to other non-KEEL subsystems for further processing.

KEEL outputs could be part of a local feedback loop.

KEEL engines can be part of a feedback loop where the output of the system is connect back to the input through some other circuitry.

KEEL outputs could be part of a distributed feedback loop.

KEEL outputs could be fed to other external devices which, in turn, feed data back to the input of the KEEL engine. The other devices could be local or remote to the KEEL engine.

Warning messages could be triggered.

The outputs from the KEEL engine could be used to trigger warning messages. The warning messages could use other outputs to describe the warning in relative terms.



Information messages could be triggered to indicate status. Analog values could be included to explain subjective interpretation.

KEEL engines can be used to supply variable information in the form of informational messages. Complex messages could be structured from multiple variable output signals.

Commands to operators could be generated.

KEEL engines interpret information and provide outputs that represent a balancing of the inputs. These values can be used to generate complex commands to an operator.

Logging of information could be triggered. KEEL could log its own decisions or it could log other inputs and outputs.

The outputs from KEEL engines could be logged for historical records or for audits.

The inputs to the system could also be logged. If the log format is in XML compliant with the KEEL Input Schema, then the data could be used in the development environment to recreate the decision-making model for exact interpretation.

KEEL could cause state changes of the system to take place based on subjective evaluations.

KEEL engines interpret input information and drive outputs. These outputs could drive an external state machine that could cause the equipment holding the KEEL engine (or any other system with or without the KEEL engine) to change state. In this case, the KEEL engine is supplying inputs to the state machine.

KEEL could generate diagnostic interpretations.

Beyond just generating processed / interpreted information, KEEL engines can interpret diagnostic information and explain the interpretation in detail.

In addition to explaining the interpretation, it can provide the information to explain why other diagnostic interpretations are not considered.

The sources of input data

KEEL engines can accept inputs from almost any type of data source, as long as the data can be transformed into the normalized data format required by the KEEL engine.

When the input is textual or verbal, it will have to be transformed into the normalized format.



Human operator

In systems where the human operator is part of the system there is the potential that the operator will be providing input data to the system.

For example, the operator could be supplying input data to the system as part of the job function. The operator could be reading values or recording physical observations about characteristics of the problem domain. This could be a doctor that records physical symptoms of the patient or of the environment that may contribute to the symptoms.

In other cases, the operator could be directed to take specific measurements. An example might be an automotive service technician that could be directed to take readings in an automotive electrical system to try and isolate the problem.

Inputs from human operators are commonly gathered through some kind of Human Interface Device that will transform the information from human terms to formats more conducive to digital processing. This might be via a keypad, a pushbutton, or in some cases it might be voice input. It could also be in some form of visual form where information is generated by physical movement. It is possible that any of the human senses could trigger inputs to a KEEL system.

Sensors

Sensors of all types can be used as inputs to a KEEL system. As long as the information can be transformed into one or more normalized input values, it can be interpreted by a KEEL engine.

Sensors exist to detect and measure almost all physical states. For example: time, temperature, pressure, torque, speed, acceleration, distance, density, color, edges, shapes, counts, volume, etc. There are probably sensors to measure anything for which a value can be assigned to it.

Collections of sensors can also detect and measure non-physical information: stress, truthfulness, pain. These values are determined with some algorithm that synthesizes the information.

Databases

Databases are used to store historic and synthesized data. This data can be manipulated by any number of mathematical processes to provide running averages, identify trends, detect shifts, etc.

The result of database queries can generate numeric information that can be used as inputs to KEEL engines.



Databases that are constantly updated have the ability to send evolving data to KEEL engines and thus tune the KEEL engines with new data.

External Data Sources

In addition to databases, external data sources can be any device or software application that generates information.

For example, machine tools may have counters embedded in them that count completed operations or completed orders. This information is gathered as the equipment operates and can provide input information to KEEL engines.

A clock or calendar is another example of an external device that can generate information for a KEEL engine. These devices generate time related information.

A communication network might generate traffic information.

Other KEEL Engines

KEEL engines may be components of a larger cognitive system. In these cases it is likely that one KEEL engine will feed other KEEL engines.

The KEEL FBD tool provides a mechanism for integrating multiple KEEL engines in a single application.

A more loosely coupled solution would be to connect KEEL engines across a network or some other connectivity approach.

Locally accumulated data

A KEEL engine will be embedded in a device or software application.

It is likely that the device or software application will be performing functions in addition to the cognitive process associated with the KEEL engine. In these cases other values generated by the application may be used as inputs to the KEEL engine. Certainly diagnostic and prognostic data generated by a device might be used to drive a KEEL engine.

Preprocessed data

Preprocessed data can exist anywhere in a system. This preprocessed data could have gone through a validation process or a transformation process. It could carry with it confidence data or some other biasing information that could be used in conjunction with the preprocessed data. It could be accumulated locally or it could exist



anywhere in the system where it could be move to the KEEL engine for interpretation and processing.

Control Signals from Other Devices

Control Signals from pieces of equipment or software applications can be used as inputs to KEEL engines.

In some cases KEEL engines are part of autonomous devices. They react to their surroundings and decide what to do for themselves. In some of these cases, the KEEL engine could intercept control signals from another device that are directed to perform operations for that other device. This information could provide intelligence for the device containing the KEEL engine.

Connectivity

The ability to install KEEL engines at any point in a system makes this a valuable attribute where components of the system are likely to be distributed across different pieces of equipment in different locations.

KEEL engines can be connected by any media and in any format as long as the data is converted to the normalized format before triggering the KEEL engine to process it.

Directly wired to source

In its simplest form a sensor can be directly wired to an input pin on a microprocessor where the signal is transformed to a normalized data format used by the KEEL engine.

The same is true for the output. In its simplest form the normalized data output from the KEEL engine is transformed before sending it out a pin on the microprocessor where a wire carries the signal to an actuator (control point).

A direct wire is the simplest form of network.

Network connected - any topology

Connectivity to and from KEEL engines can be accomplished with any type of network with any topology.

Some wired networks might be termed point to point, multi-drop, token passing, star, web, loop, trunk, etc.

Messaging techniques might include: Broadcast, Store and Forward, Directly Addressable, Group Addressable, All-call.

Any message packaging technique might be used: structured or unstructured, packed, block mode, etc.



Any character encoding can be used: ASCII, Async, Bisync, Isochronous, or any other.

The data can be encrypted or non-encrypted.

The choice of network connectivity is left to the system designer.

Infrared connection

The KEEL engine is not restricted to any specific connectivity to its inputs and outputs. Infrared links can be used.

Supplied by the same processor running the KEEL engine

Because some data sources and data sinks for KEEL engines will be within the same microprocessor, input and output data can be generated and consumed locally.

Radio Frequency

KEEL engines are independent of the connectivity between inputs and outputs and the KEEL engine. Radio frequency connectivity is appropriate for some applications where wired and infrared connections are not appropriate.

Development Process:

Determine where KEEL engines might be located in the system and what information will be exchanged

This is where the number of KEEL engines will be identified to satisfy the system need.

This is also where the information model will be defined: What input information is needed at each KEEL engine and how that information will flow through the system.

Define the information hierarchy which includes how and when information is accumulated

Some systems will fit in a "chain-of-command". The concept of authority needs to be considered in these types of systems.

This will dictate who is a supplier of information and who is a receiver of information.

This is where the concept of trust needs to be included in the model.

The concept of risk may also be considered.

Plan for staged introduction



In systems that might require multiple KEEL engines, consideration for a staged introduction might be appropriate.

Since KEEL engines operate autonomously, this is primarily an issue that is driven by other parts of the system.

If cognitive technology is to be included in the overall system, then it should be scheduled for introduction when it can be tested with the availability of its inputs and outputs.

Evaluate KEEL segmentation

KEEL engine segmentation is an issue that is required with distributed systems. It should also be considered with complex cognitive situations.

The KEEL FBD tools provide support for the integration of multiple KEEL engines into a single compile for a localized solution.

There is also the potential for integrating multiple independent segments into a single KEEL engine. In situations where one is dealing with simple cognitive processes, it might be appropriate to include several of them in the same engine.

For each KEEL engine, define the expectations (outputs) from the system

The outputs of the system can drive external controls, provide information or logging data, drive external logic, provide warnings or triggers, or drive other processing engines (like other KEEL engines) or hard coded logic.

The outputs of the system define what the KEEL engine is trying to accomplish.

For each KEEL engine, identify the sources of information

The sources of information are the inputs to the system as viewed from the outside of the KEEL engine. They can come from sensors, databases, human operators, other KEEL engines, other control systems, or internal logic (like self diagnostics and prognostics or internal calculations).

KEEL General:

This section identifies the general benefits that could be derived from a KEEL based solution.

Judgmental decisions by trained operators are potentially "tricked" into overlooking critical attributes

There are some applications where there is an attempt to trick humans.

Magic shows attempt to redirect attention while the trick is performed.



Some markets like airport security target people that may try to trick the system. A terrorist is not going to advertise he is a terrorist.

When people are trained for airport security, they are trained to look for specific attributes. These are the rules.

KEEL engines are rule based systems. The rules identify the trigger points.

While the perfect airport security agent will never miss a critical attribute, human nature makes them susceptible to structured trickery.

A KEEL engine will perform according to its rules.

Human experts take too long to make judgmental decisions

Human experts are trained to perform a task. This works well when the task operates in normal ways.

However, when humans are "surprised", it takes them some amount of time to react.

Adrenaline is used to supercharge the human in special circumstances. This accelerates their response mechanism and makes them more aware of their surroundings.

Even with adrenaline, however, reaction time is based on the complexity of the task.

Computers running structured code react to emergencies (events) in a structured way.

Computers, however, cannot watch out for everything. The code to develop this type of system would be too complex.

The adaptable nature of a KEEL engine may provide a middle ground: faster than a human and not so complex that one would have to write too much code to respond.

The dynamic nature of a KEEL engine enables it to handle complex situations in adaptable ways.

Applications where the judgmental decisions must be explained

While not all decisions or actions need to be explained, there are a number of reasons for having an explainable system.



First, it is difficult to enhance a system when you don't know why it is doing what it is doing. With a KEEL system, if one takes a snapshot of the critical inputs, those inputs can be loaded into a KEEL engine where the reasoning can be investigated.

Some systems need an explainable solution for legal reasons.

A system that creates explainable actions may be more marketable and may be more likely to receive market acceptance.

Complex situations where it is uneconomical to develop and maintain straight line code (IF, THEN, ELSE)

It is very expensive to develop software. Complex software is prone to logic and typing errors.

Large complex systems are brittle and break with unexpected, untested situations.

KEEL systems allow the development of complex systems without writing code. The decision-making model is developed graphically and the code is created automatically. The model can be tested from within the toolkit, before it is translated to source code.

The same cognitive model can be translated into multiple languages at the click of a button.

Situations where the environment is dynamic and the importance of information changes and the system must react to change

A key attribute of KEEL systems is that the dynamic importance of information is built into the KEEL technology.

KEEL was designed to accept and adapt to the changing importance of information.

Information changes in importance when it is being evaluated from different time and space aspects. (For example, the temperature is important because you are close to the source. It is not important if you are far away from the source. What is NOW is more important than what is FAR IN THE FUTURE if you are thinking about a problem now. It is less important now if you are addressing a strategic problem.)

Situations where there is an advantage to be able to create one design and execute it on multiple platforms: device, software simulation, web

In some circumstances there is a large value for being able to demonstrate the same model in a device, in a simulator, and on a web page.



Using the KEEL Toolkit, the same design can be implemented in C, C#, VB, VB.NET, Flash, Java, PLC Structured Text.

When it is important to demonstrate the cognitive technology in multiple environments, KEEL can provide a significant advantage.

Where architectural issues may prohibit other solutions (KEEL technology is architecture independent: localized, distributed, web based, multiprocessor, etc.)

KEEL engines are implemented as two or three subroutines in any of a variety of languages.

One subroutine is called to initialize the arrays with data.

The second subroutine is scheduled when appropriate. Before this routine is called, the KEEL arrays are loaded with input data. Then the second routine is called repetitively until a flag is set indicating that a stable system has been determined. After that, the outputs from the system are distributed to the appropriate places.

This simple API and small subroutine set allows KEEL engines to be integrated into a variety of system architectures.

KEEL engines don't care where the input data come from or where the outputs are distributed.

This makes the KEEL engines appropriate for almost any system configuration.

The architecture selection is left to the system architect.

Human experts are required to interpret information to make the best decisions or take the most appropriate actions

KEEL engines interpret information in a human-ike manner. In this light, KEEL technology is an expert system that makes decisions or takes actions using rules established by the designer.

Like human decision-making, KEEL engines utilize a linkage of information to solve problems. An input may impact a number of problem domains; each in a different way. A single problem domain may impact a number of other problem domains in a variety of ways.

The linkages defined for the KEEL engine are the same as the ways that a human might link pieces of information.



The KEEL toolkit provides a unique way to document the human decision-making model for specific applications.

Devices must operate autonomously and make judgmental decisions on their own

Each KEEL engine has its set of inputs and outputs.

When the KEEL engine is scheduled to evaluate the inputs, it iterates until a stable answer to all of its problems is achieved.

Each KEEL engine is a stand-alone function. If a complete system is incorporated into a single engine, then a complete stand-alone solution is developed.

A system can be built with one engine or it can be built with several engines that are integrated into a single autonomous solution by using the KEEL FBD tool. Services provided within the KEEL Toolkit support the software engineer's need to compile multiple engines with a single compile.

KEEL technology has been developed to specifically address the needs of adding cognitive technology to devices in order to provide autonomous operation.

KEEL technology supports addressing the judgmental decisions required when there is a need to make subjective decisions in a human-like manner.

Devices can make control decisions when human operators are not present

Because KEEL engines can operate autonomously, they are able to provide backup to human operators when the human operators are unavailable.

KEEL engines can make the same judgmental decisions as their human operators. These judgmental decisions are appropriate for making control decisions.

These control decisions can be binary (on/off) or relative (analog). Just like a human operator, a KEEL system can take observed data (inputs) and apply cognitive judgmental rules that are defined graphically and make the control decisions.

When the small memory footprint of a KEEL engine is an advantage

KEEL technology is implemented in two or three small subroutines. The size of the subroutines does not expand if the system increases in size or complexity.



The remainder of the system is made up of tables. These take much less space than "code".

This allows KEEL engines to run in 8 bit microprocessors and above.

This is important in many "device" applications.

Repetitive judgmental decisions are prone to error

Some human activities or occupations require that those humans are trained to observe and react to situations. This could be an airport security guard or it could be a medical diagnostician.

The airport security guard is asked to look for things out of the ordinary. This triggers increased scrutiny of passengers and of luggage.

The medical diagnostician is trained to look at diagnostic tests.

Both of these activities are repetitive. There are potentially large amounts of data (characteristics) to observe.

The decisions or observations by the reviewer are prone to error, just by the number of repetitive judgments that are made.

The airport guard that hasn't identified a problem passenger in five years may get passive as time goes by.

The medical diagnostician that never finds a disease may miss the one critical test that identifies a particular diagnosis.

Summary:

Autonomous vehicles will have to make subjective judgmental decisions on their own. KEEL based systems can respond to this need.

Autonomous vehicles will have to make control decisions by interpreting information in a human-like manner to achieve their market expectations.

Autonomous vehicles will have to make decisions as fast (or faster) than their human counterparts. KEEL based systems can provide this functionality.



The development time for autonomous vehicles cannot be prohibitive. There must be a way to develop this cognitive capability in a timely manner. The KEEL toolkit allows the development of complex cognitive systems rapidly.

In some cases there is an advantage to use KEEL based designs when there is a need to implement the same decision-making process in the device, a simulator, and on a web page.

The small memory footprint makes KEEL the preferred solution when memory is limited.

Disclaimer

This application note suggests the potential for KEEL technology to respond to certain market needs. The end users are totally responsible for assuring that the technology performs as expected.

The application note may also assume that certain external technology exists to support the KEEL engine in an effective manner. This may or may not be accurate in all cases.